

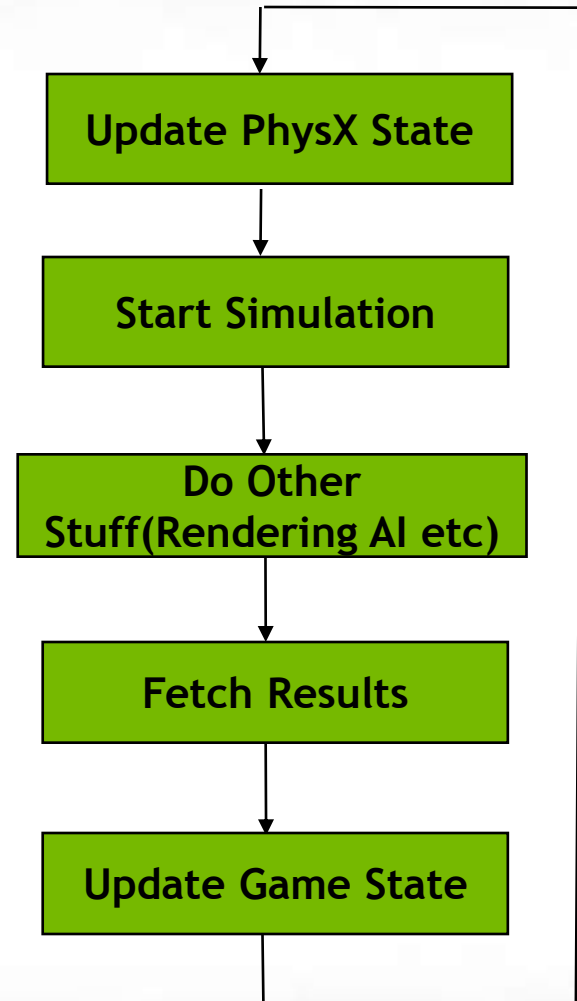
PhysX & APEX Programming and Optimization

Purpose of this Presentation

- Understand the story behind the Scene
- Tips on how to create similar effect in a Game engine
- Tips on Optimization

PhysX SDK Workflow

- PhysX Workflow
 - Asynchronous Simulation
 - PhysX SDK natively is multi-threaded
- PhysX-related Game State
 - Position
 - Velocity
 - Normal
 -



PhysX Fluid/Particle

- From 《P.L.A》 Benchmark

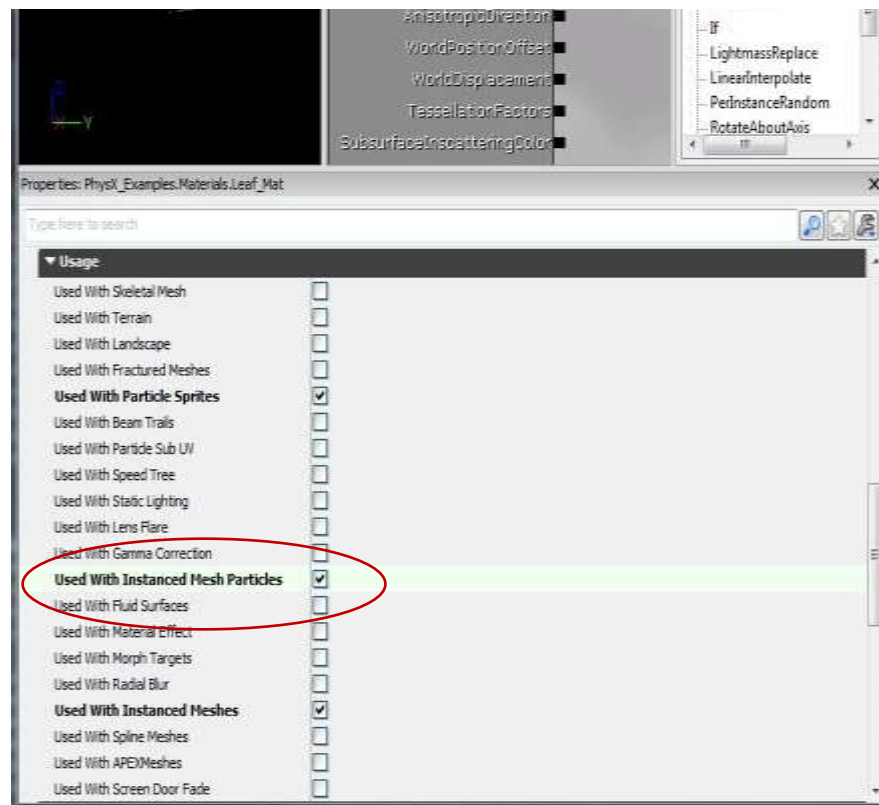


PhysX Particle Creation

- Creation of Particles
 - Directly calculate states(pos, vel) of particles
 - Create All particles upfront
 - Insert/Delete Particles each frame
 - Use NxFuildEmitter to emit particles automatically
- Main Properties
 - Collision radius and collision response
 - Velocity control of particles
 - SPH(fluids) only properties, e.g., viscosity and surfaceTension

Hardware Acceleration

- To increase the number of Particles
 - GPU PhysX particle (NX_FF_HARDWARE)
 - Adopt Instancing
 - UE3 material setting →

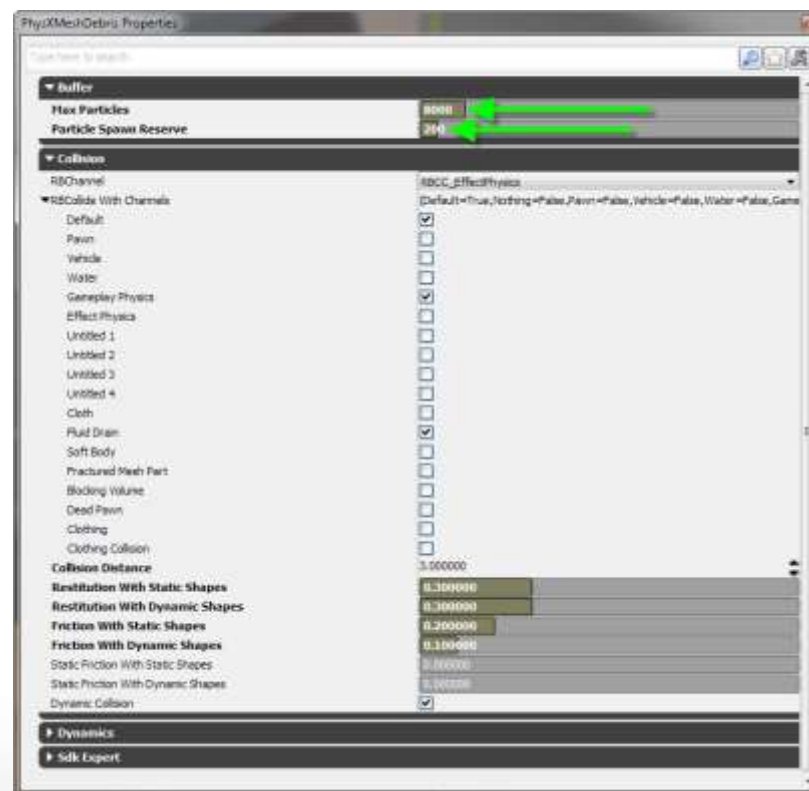


Share PhysX Particle SDK Sample

```
UserData Fluid Sample (hardware) www.fraps.com  
F1 for help  
GpuHeapUsageTotal = 3072, max = 6894 kB  
GpuHeapUsageFluid = 1024, max = 4712 kB  
GpuHeapUsageUtils = 0, max = 134 kB  
GpuMeshCacheUsage = 0, max = 0 kB
```

Share PhysX Particle

- Max Particles
 - Maximum Number of Particles in a Particles system
- Particle Reserve
 - Old Particles in the FIFO will be deleted
 - Maximum Number of Particles to emit in a frame after the Maximum Particle number is reached



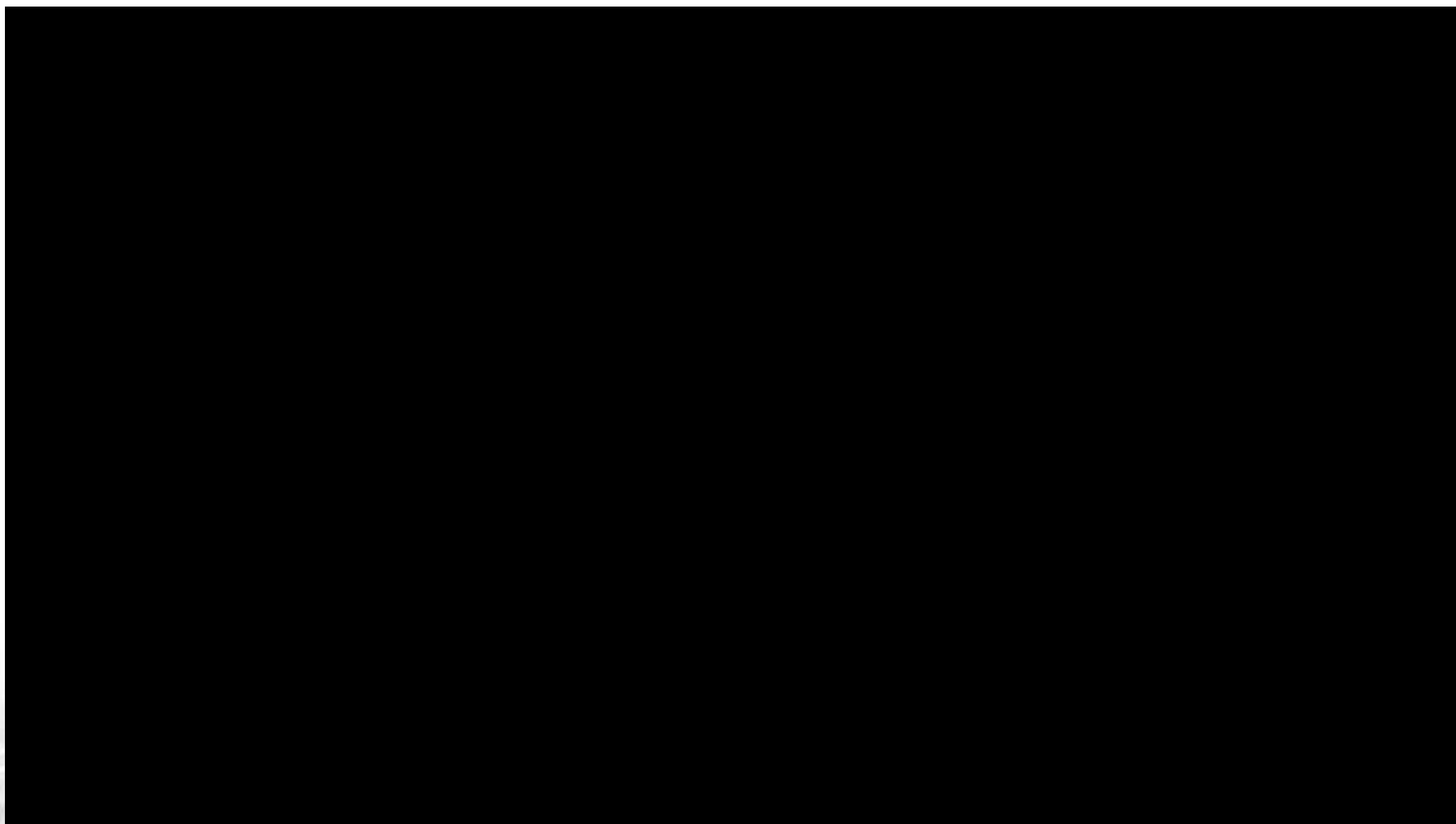
PhysX Cloth

- 《P.L.A》 Cloth Sample



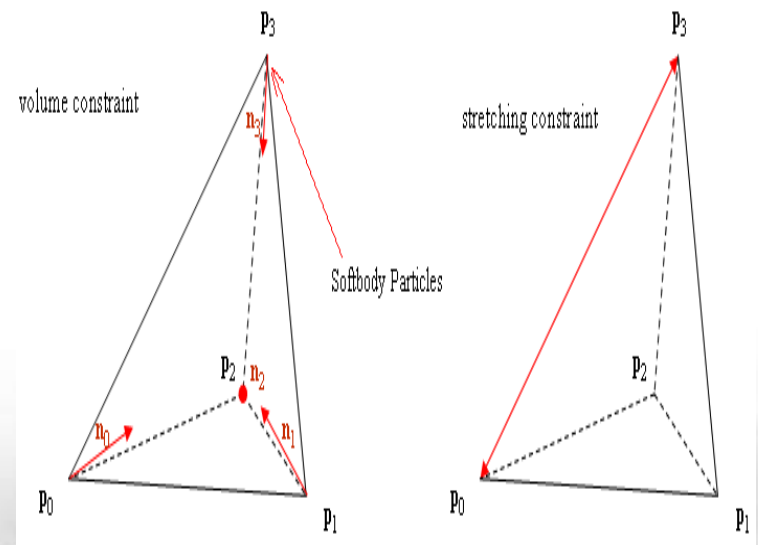
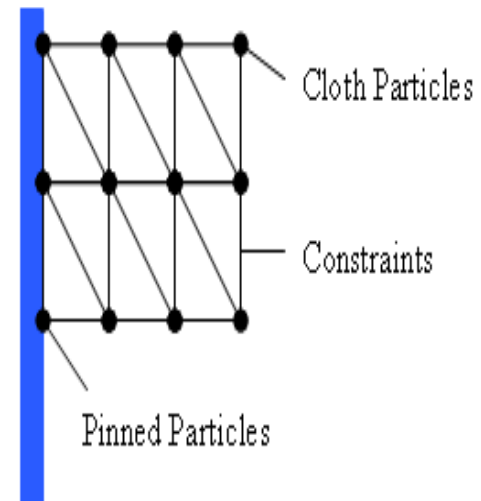
PhysX Cloth

- 《P.L.A》 Cloth Sample, Explosion Interaction

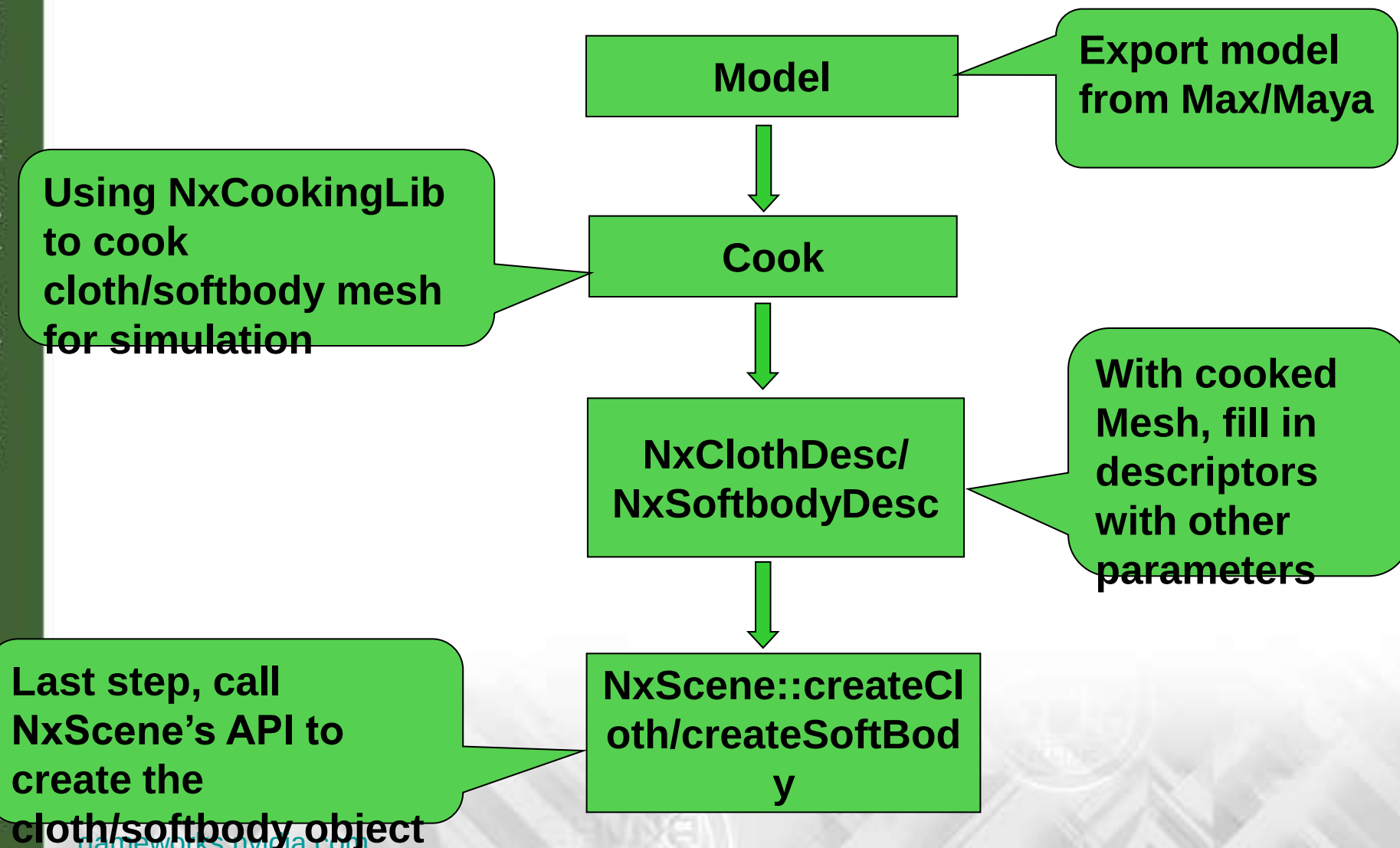


Deformables

- Cloth & Softbody
- Particles + Constraints + Meshes
 - Cloth: triangle mesh
 - Softbody: Tetrahedral mesh
- Special features
 - Tearing
 - Self-collision
 - Pressure



Deformables Creation Process

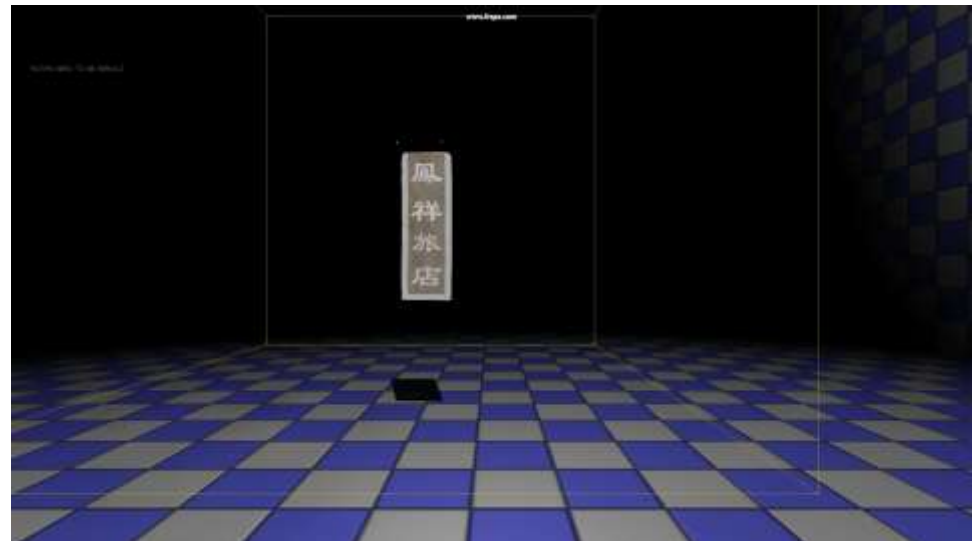
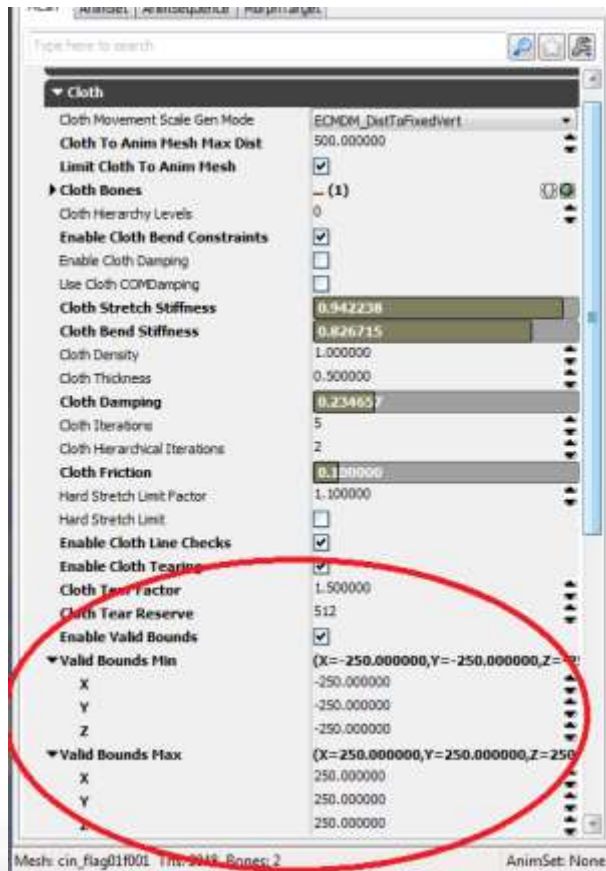


Cloth Optimization

- FreezeWhenNotRendered(pseudo-code)
if (Cloth out of view frustum)
{
 Cloth->setFlag(NX_CLF_STATIC)
}
- Cloth stops at the last position.
- Simulation stops to increase performance

Optimization for Tearable Cloth

- ValidBound Setting and Sample

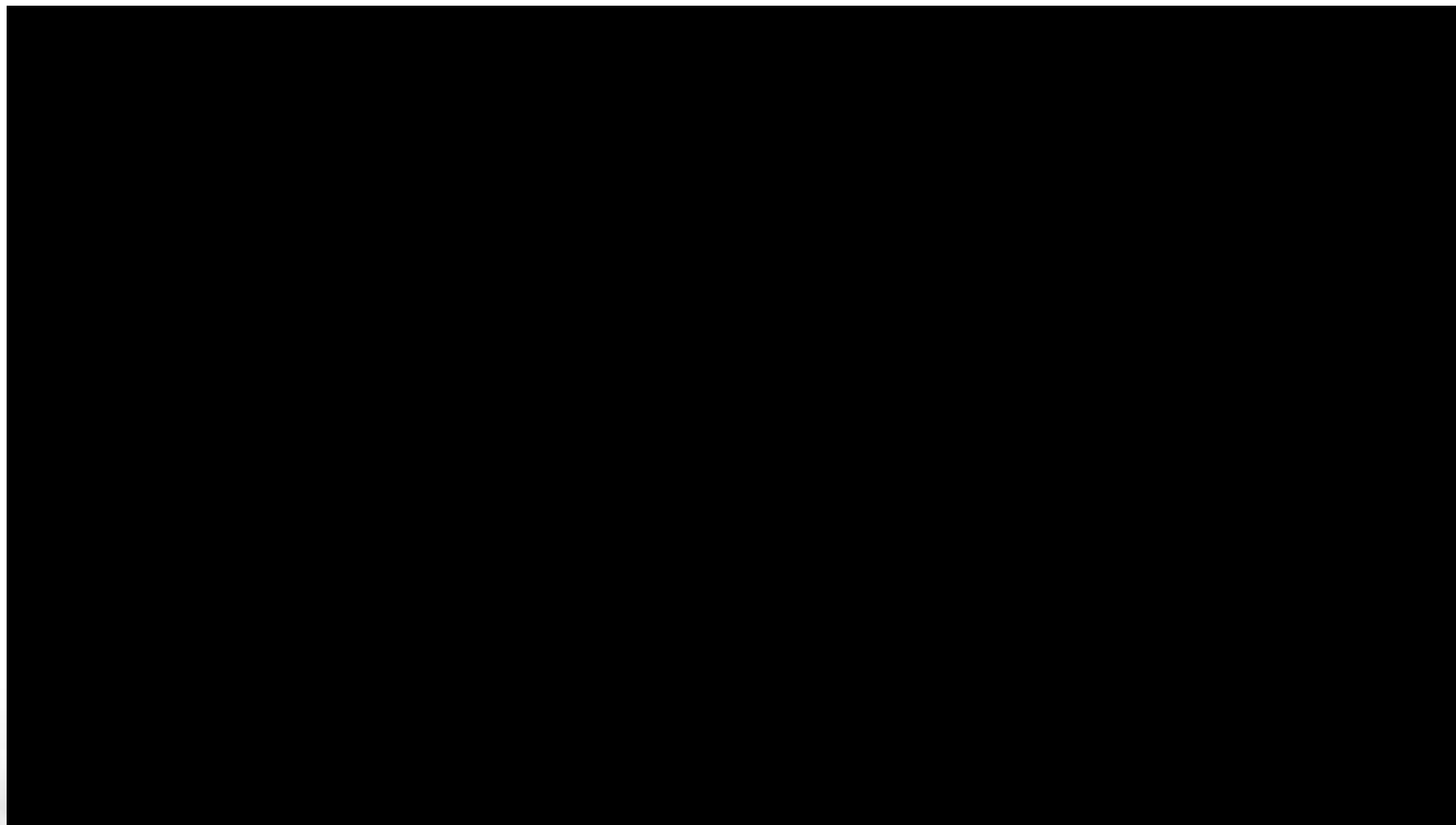


ValidBound Opt Setting

- Cloth Flags
 - [NX_CLF_TEARABLE](#)
 - [NX_CLF_VALIDBOUNDS](#)
- [setValidBounds](#)(const [NxBounds3](#)& validBounds)
 - A World space cube
 - Cloth verts outside this cube will be deleted
 - Note: to remove the rendering triangles as well

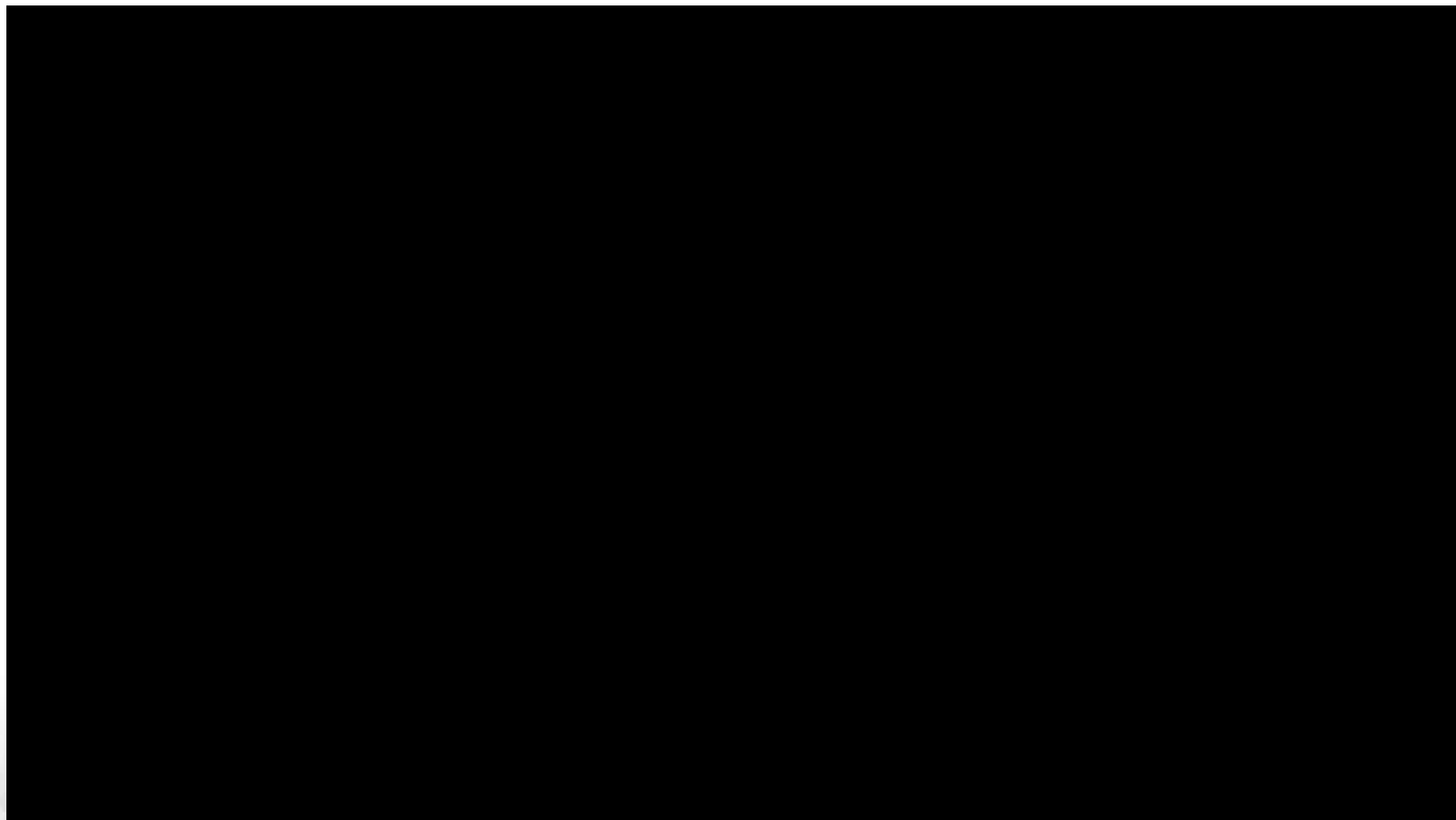
APEX Destructible

- 《P.L.A》 Destructible Scene



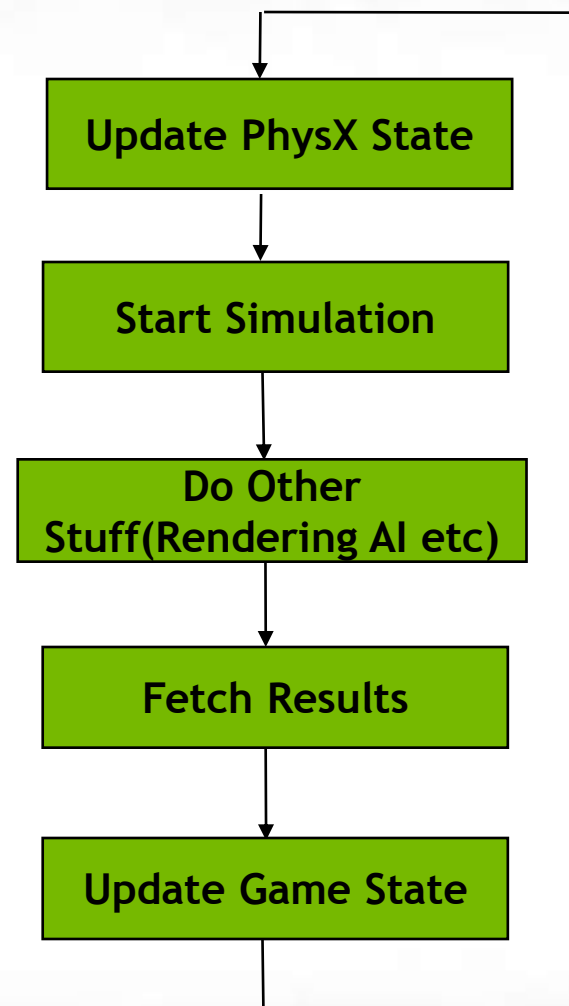
APEX Destructible

- 《P.L.A》 Destructible Scene



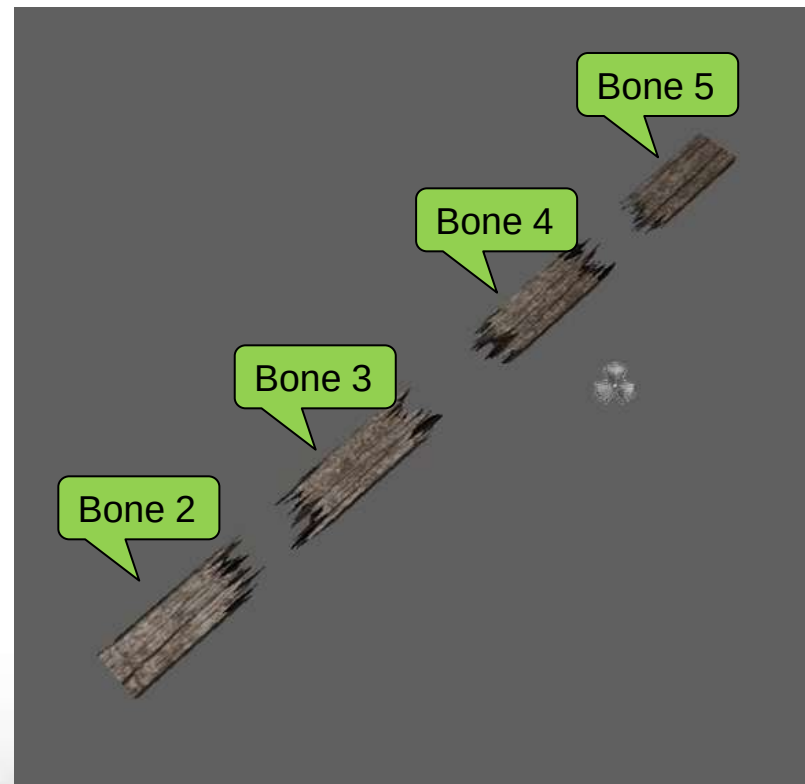
APEX vs PhysX Workflow

- PhysX
 - Simulate/fetchResults
 - Update Game State
 - Position, Rotation, Velocity, Normal, etc.
- APEX
 - Load Assets
 - Simulate/fetchResults
 - Update Game State
 - Vertex Buffer, Index Buffer, Bone Buffer, etc



Rigid Skinning Rendering

- Single VertexBuffer



Callback on Fracturing

- Callback function

- Sample:

```
void physx::apex::NxUserChunkReport::onDamageNotify ( const NxApexDamageEventReportData & damageEvent )  
{  
    for each DamageEvent  
    {  
        Emit Fracturing Particles at the hit Location;  
        Playback Fracturing Sound;  
    }  
}
```

- [NxApexDamageEventReportData](#)

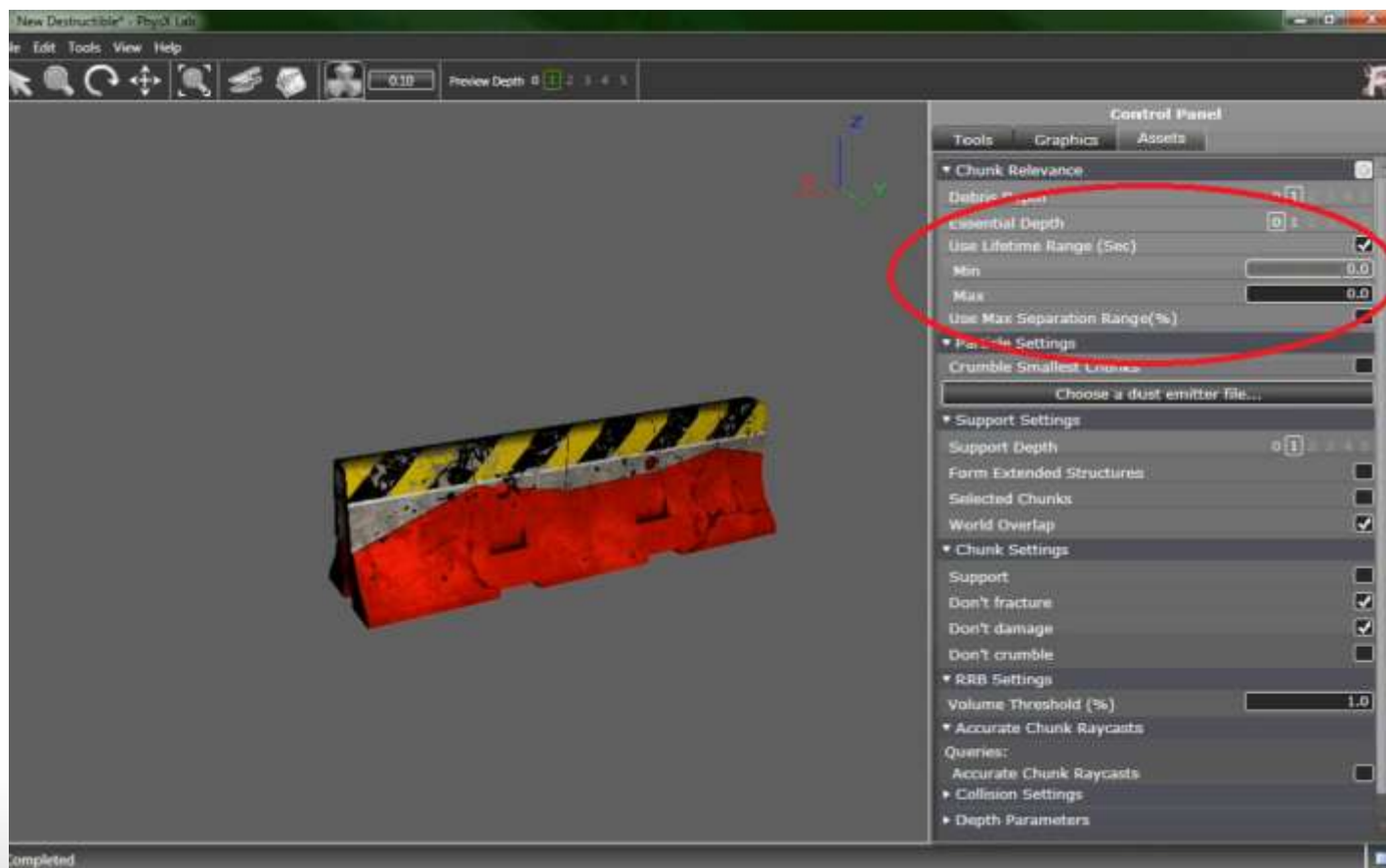
- Destructible Actor
 - HitLocation, HitNormal
 - Fracturing Chunk index
 -

Jitter

- Problem:
 - Sometimes a pile of PhysX convexes can bounce around unnaturally for a long time.
- Possible Solution
 - Increase damping
 - Increase angular damping parameter to a value of 10-15
 - Lose energy
 - Increase friction and lower restitution
 - Equalize masses
 - If there is a large mass difference the body with the smaller mass can move quite a lot and keep the whole pile moving.
 - Put them to sleep
 - Increase the sleep energy threshold value will cause destructible chunks to fall asleep more easily.

Authoring Optimization

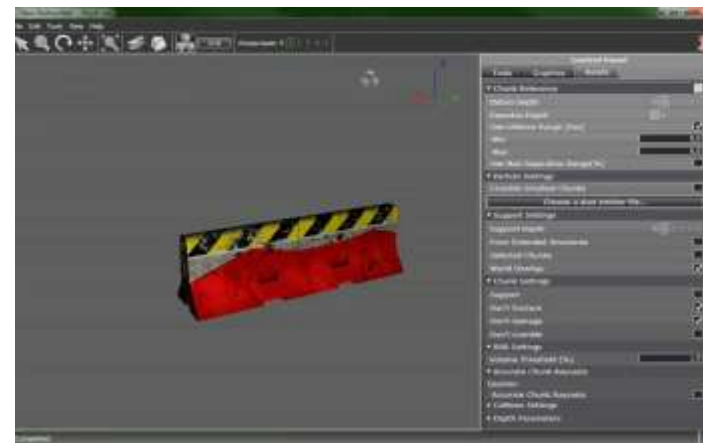
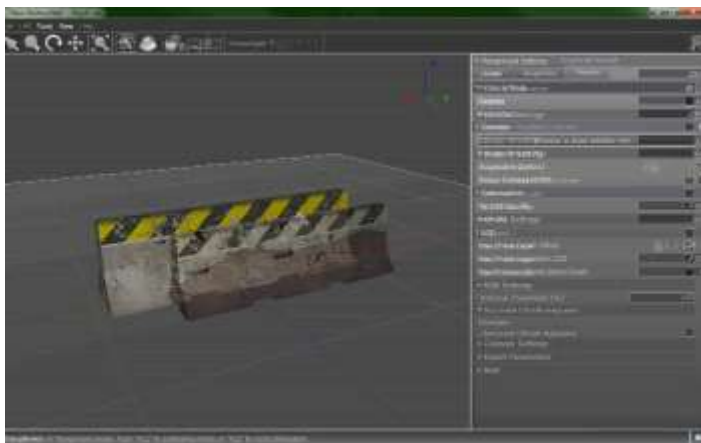
- Debris Timeout



Authoring Optimization

- Debris Setting with Code

- `setParamBool(*params,"destructibleParameters.flags.DEBRIS_TIMEOUT", true);`
- `setParamI32(*params,"destructibleParameters.debrisDepth", 1);`
- `setParamF32(*params,"destructibleParameters.debrisLifetimeMin", 0.0f);`
- `setParamF32(*params,"destructibleParameters.debrisLifetimeMax", 0.0f);`



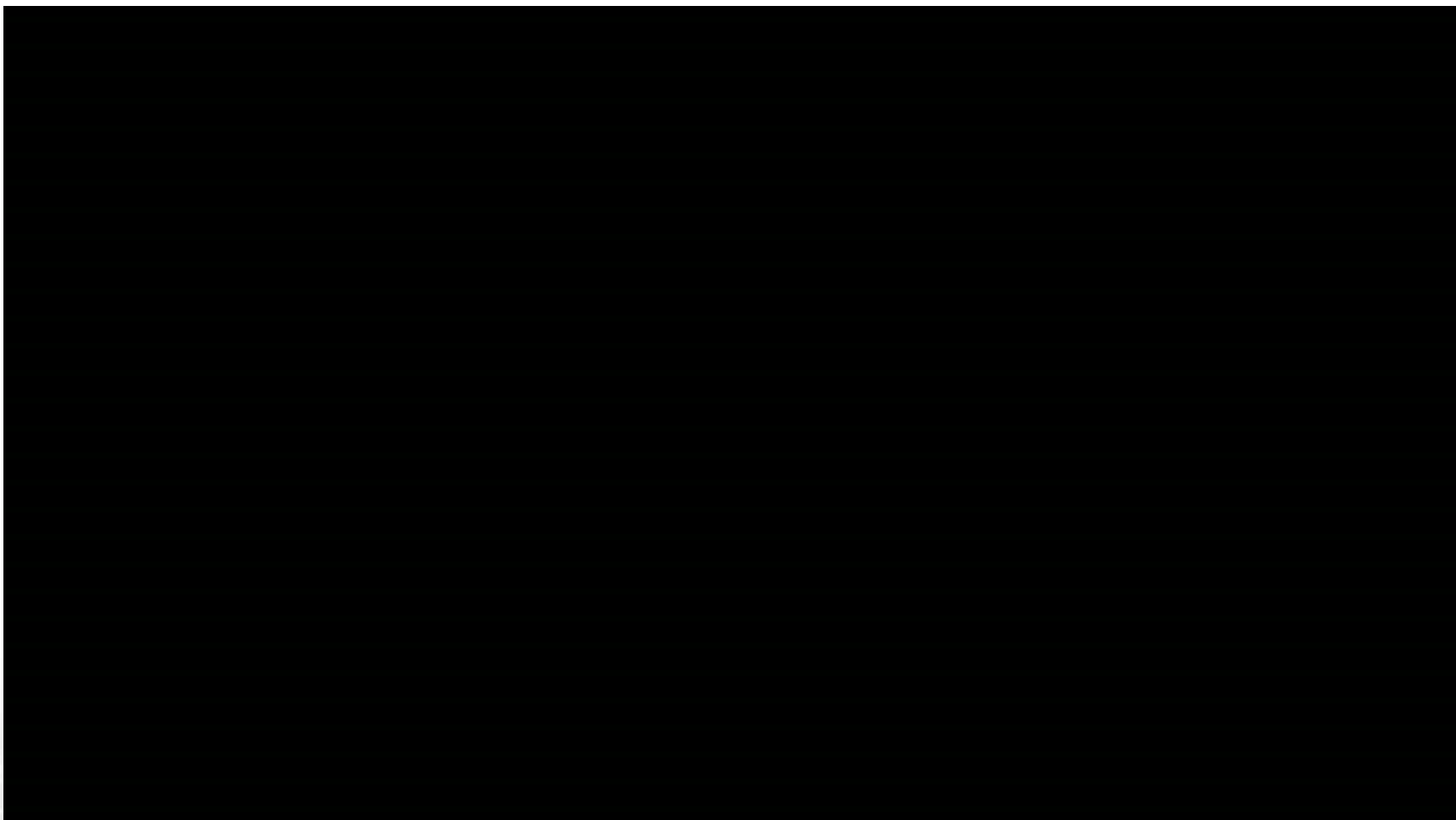
- Similar for *Debris Max Separation*

Simulation Optimization

- Avoiding too many chunks on screen
 - setMaxDynamicChunkIslandCount
 - Maximum number of dynamic chunks island in the scene.
 - setMaxChunkCount
 - Maximum number of dynamic chunks in the scene. No less than maxDynamicChunkIslandCount
 - setLODResourceBudget
 - Overall LOD resource setting for an APEX scene(including destructible)
 - setMaxActorCreatesPerFrame
 - Cap the maximum number of Destructible actors in a frame

Hardware Acceleration

- Simulate Rigid body on GPU--GRB



Q & A?